

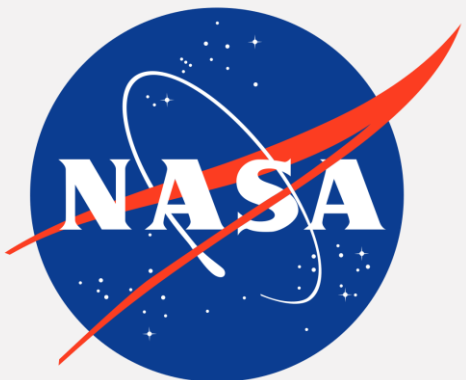
Cluster-based characterization of multi-dimensional tropospheric ozone variability in coastal regions: an analysis of lidar measurements and model results

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AMS 2022 Oral Presentation

Session: Addressing Air Quality Challenges at Urban–Land–Water Interfaces
during Recent Field Studies. Part I



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Goal: Use multi-dimensional lidar measurements from campaigns to evaluate simulated coastal O₃ events

-- Directly address difficulties of measuring, modeling, & forecasting the large variability of O₃ in coastal environments

-- Use 2-D high temporal & fine resolution lidar measurements to help elucidate gaps within current air quality models

-- Complete observing system (surface land & water observations, model simulations)
=> a formidable tool for evaluating air pollution in coastal regions

-- Evaluate the ability of hourly temporal O₃ measurements & improve the abilities to simulate coastal O₃ concentrations

NASA Air quality campaigns

- 3 recent air quality campaigns:
 - OWLETS 1 (O_3 Water-Land Environmental Transition Study): July 5 - August 3, 2017 ★
 - OWLETS 2: June 6 - July 6, 2018 ★
 - LISTOS (Long Island Sound Tropospheric O_3 Study): July 12 - August 29, 2018 ★
- Suite of detailed airborne & ground measurements measurements (e.g. ozonesonde, aerosol profiling - ground-based ceilometers, Pandora spectrometer, POM, etc.)
- Two TOLNet lidars used:
 - NASA Goddard Space Flight Center (GSFC) Tropospheric Ozone (TROPOZ) Differential Absorption Lidar (DIAL; Sullivan et al. 2014, 2015a)
 - NASA LaRC Mobile Ozone Lidar (LMOL; De Young et al. 2017; Farris et al. 2018)

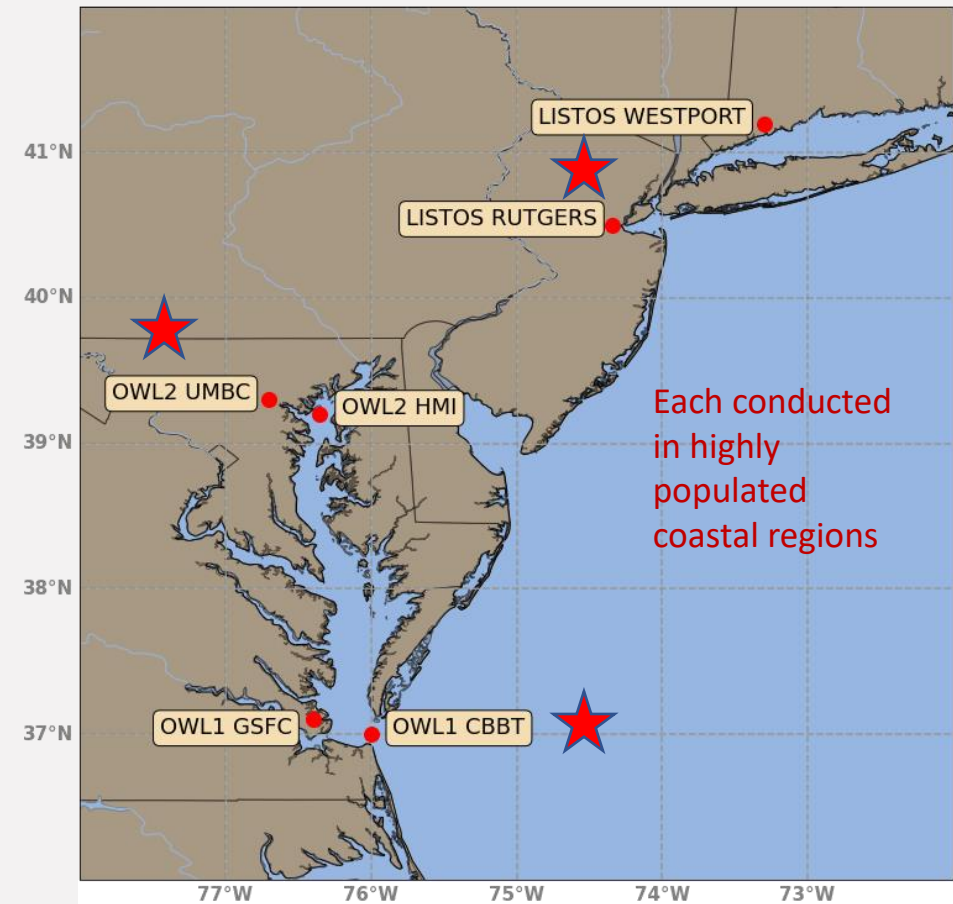


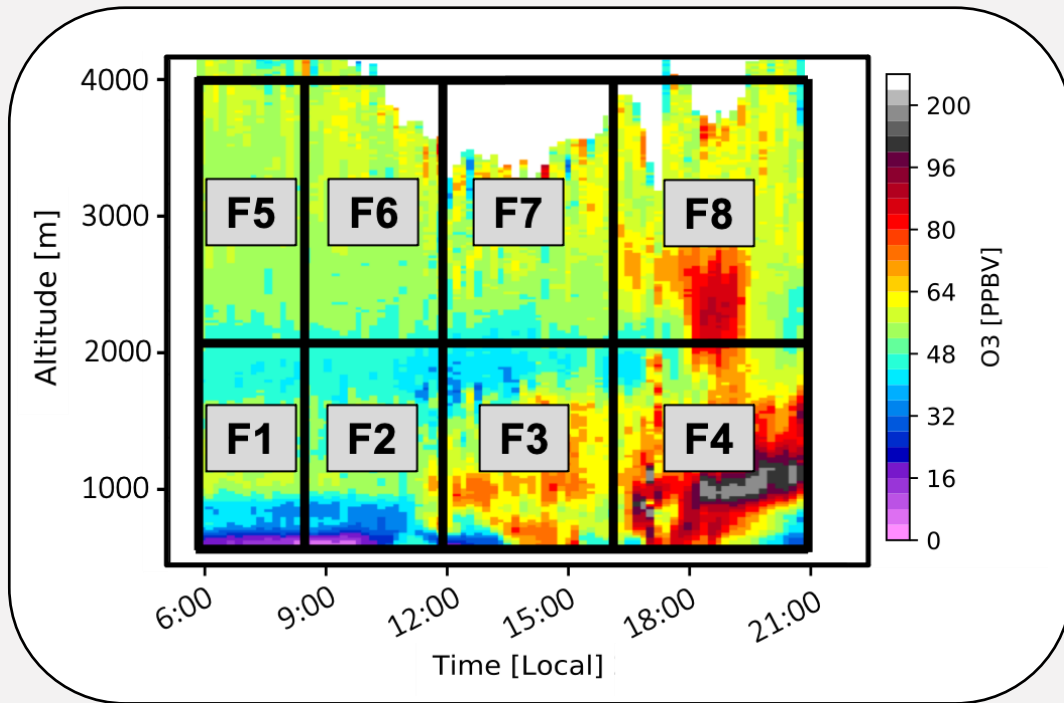
Figure 3. Inset map of Chesapeake Bay airshed in Maryland, VA and Long Island Sound in NY with 6 lidar monitoring locations used for OWLETS-1, OWLETS-2, & LISTOS (highlighted & labeled).

91 individual 2-D profile curtains used from both lidars:

- 26 from OWLETS-1,
- 28 from OWLETS-2,
- 37 from LISTOS

- <https://www-air.larc.nasa.gov/index.html>

Characterizing O₃ profile curtains



- Color coding (*left*) shows a typical O₃ profile taken from a lidar instrument
 - August 6, 2018; LMOL at Westport, CT; LISTOS Campaign
 - Developed clustering method for characterizing 2-D O₃ curtain profiles from lidar measurements
 - Constrained by the goal of evaluating lower level tropospheric O₃ limitations of the lidar measurements
- Features:**

<p>▷ Altitude 2 sectors:</p> <ul style="list-style-type: none">• 0 – 2000 m (low-level)• 2000 – 4000 m (mid-level)	<p>▷ Time 4 sectors:</p> <ul style="list-style-type: none">• 6:00 – 8:00• 8:00 – 12:00• 12:00 – 16:00• 16:00 – 21:00
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- Split profiles (91 total profiles) into “slabs” based on **altitude & time**
 - F1 – F8 (*above*) indicate input feature ranges
 - Calculated average features implemented into K-Means Clustering algorithm

Clustering O₃ profiles

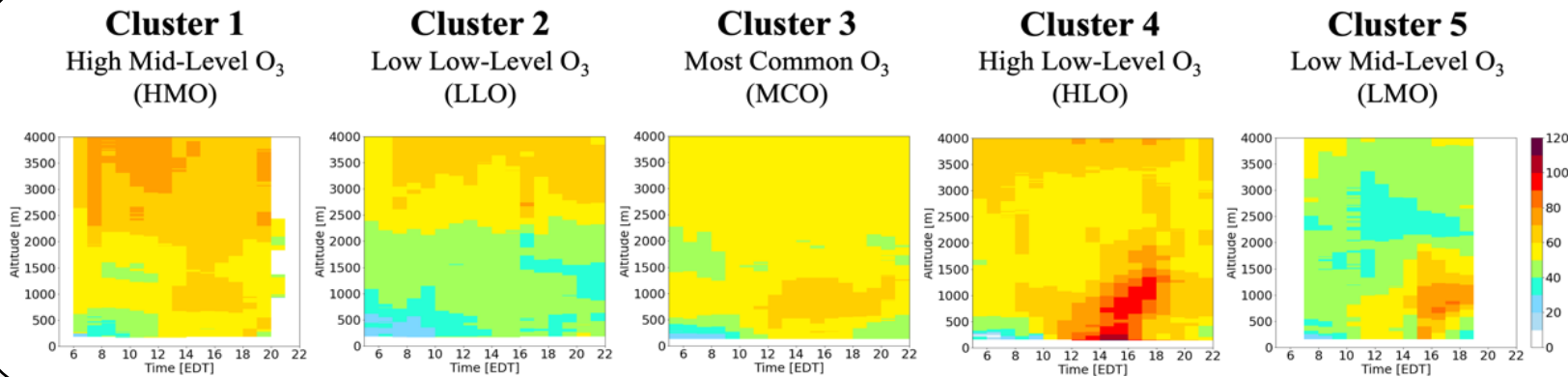
Cluster #	a) No. of profiles	b) O ₃ Max (ppb)	c) O ₃ Min (ppb)	d) T (°F)	e) WS (m s ⁻¹)
1	25	86.50	42.17	73.80	1.51
2	14	72.77	28.85	71.42	1.62
3	27	86.64	34.18	77.34	1.30
4	18	97.77	44.08	77.79	1.24
5	5	67.70	29.07	74.93	1.51

Fig. Cluster statistics

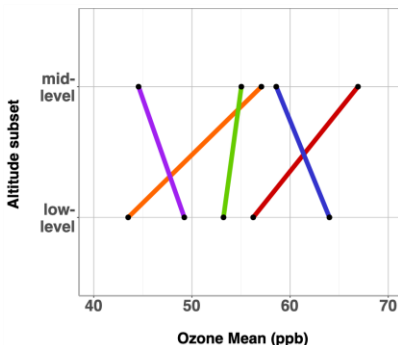
➤ Mean lidar O₃ vertical profiles for each of the clusters

Descriptions of clusters:

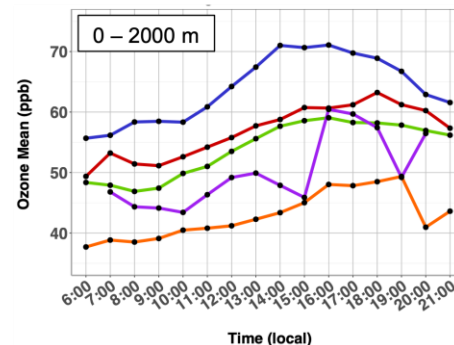
- **Cluster 1** = highest mid-level O₃ (HMO) cluster
- **Cluster 2** = lowest low-level O₃ (LLO) cluster
- **Cluster 3** = most common O₃ (MCO) cluster
- **Cluster 4** = highest low-level O₃ (HLO)
- **Cluster 5** = least common & lowest mid-level O₃ (LMO) cluster



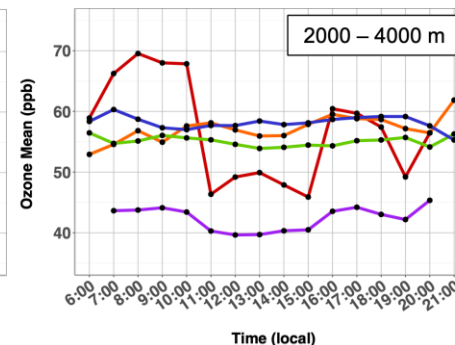
a) Altitude comparison



b) Time comparison: low-level

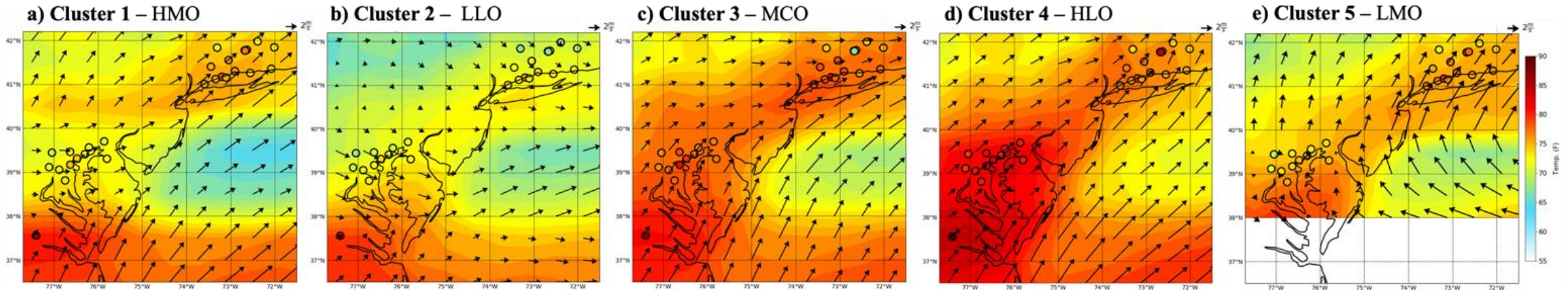


c) mid-level



- C1 - C2 - C3 - C4 - C5

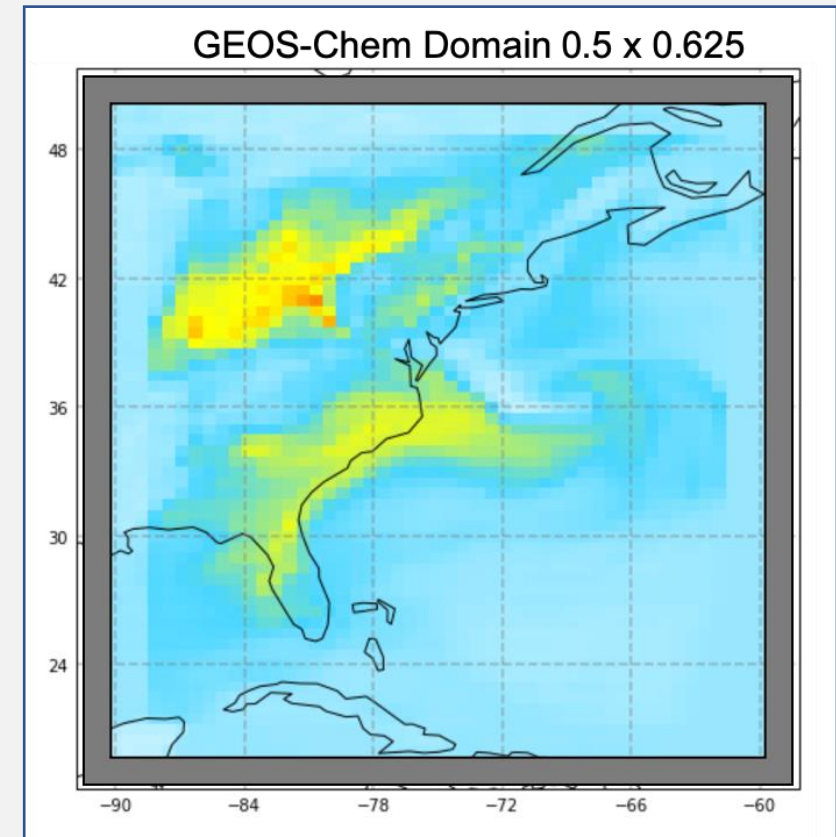
Meteorological surface analyses



- Meteorological conditions support clustered lidar O_3 profiles.
- Cluster 3 & 4 presented higher overall observed & simulated surface temperatures
- Clusters 1, 3, and 4 (highest surface O_3) -- predominant offshore, westerly wind
 - conducive to higher surface O_3 concentrations
- Cluster 2 = lowest temperatures -- cluster with lowest surface O_3 concentrations
- Cluster 5 temperatures moderately high but, in contrast, average wind speed is higher (specific over LIS)
 - wind direction is predominantly onshore (Easterly – Southerly) -- transport of cleaner marine air corroborates lower surface O_3 levels

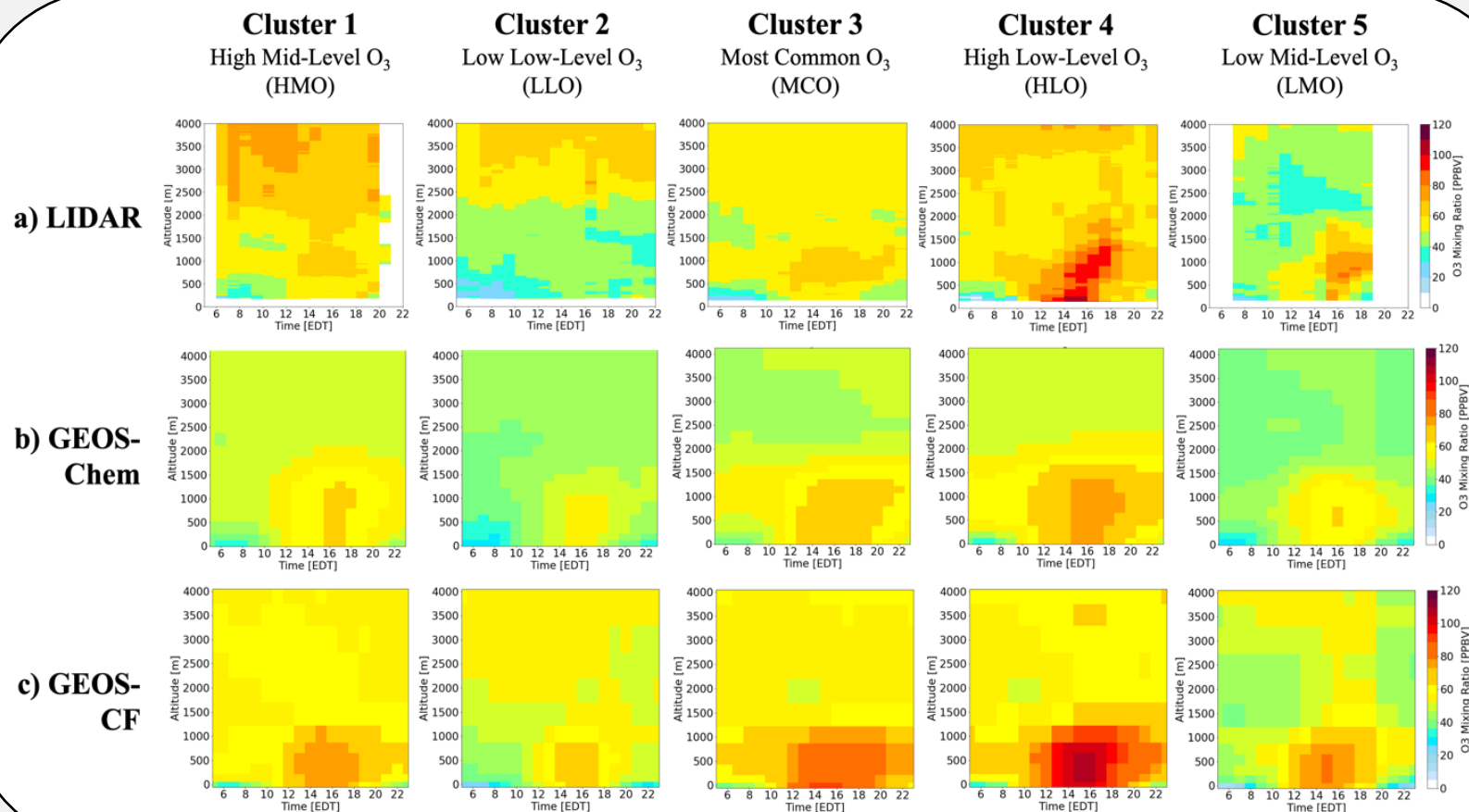
Model setup

- GEOS-Chem (MERRA2 meteorology) nested $0.5^\circ \times 0.625^\circ$ horizontal resolution ~ using $2^\circ \times 2.5^\circ$ global boundary conditions.
- GEOS Composition Forecasting (GEOS-CF) system 0.25° horizontal resolution data (<https://gmao.gsfc.nasa.gov>) (Knowland et al., 2019)
- Similar chemistry schemes
- The main model differences:
 1. GEOS-Chem => offline CTM using archived meteorology; GEOS-CF => online, simulates atmospheric composition simultaneously with meteorology
 2. GEOS-CF spatial resolution => 0.25° ; GEOS-Chem spatial resolution => $0.5^\circ \times 0.625^\circ$
 3. GEOS-CF anthropogenic emissions => Harmonized Gridded Air Pollution (HTAP; v2.2) from the Emission Database for Global Atmospheric Research (EDGAR); GEOS-Chem anthropogenic emissions => CEDS
 4. Data only available for 2018 ~ analysis adjusted for this comparison

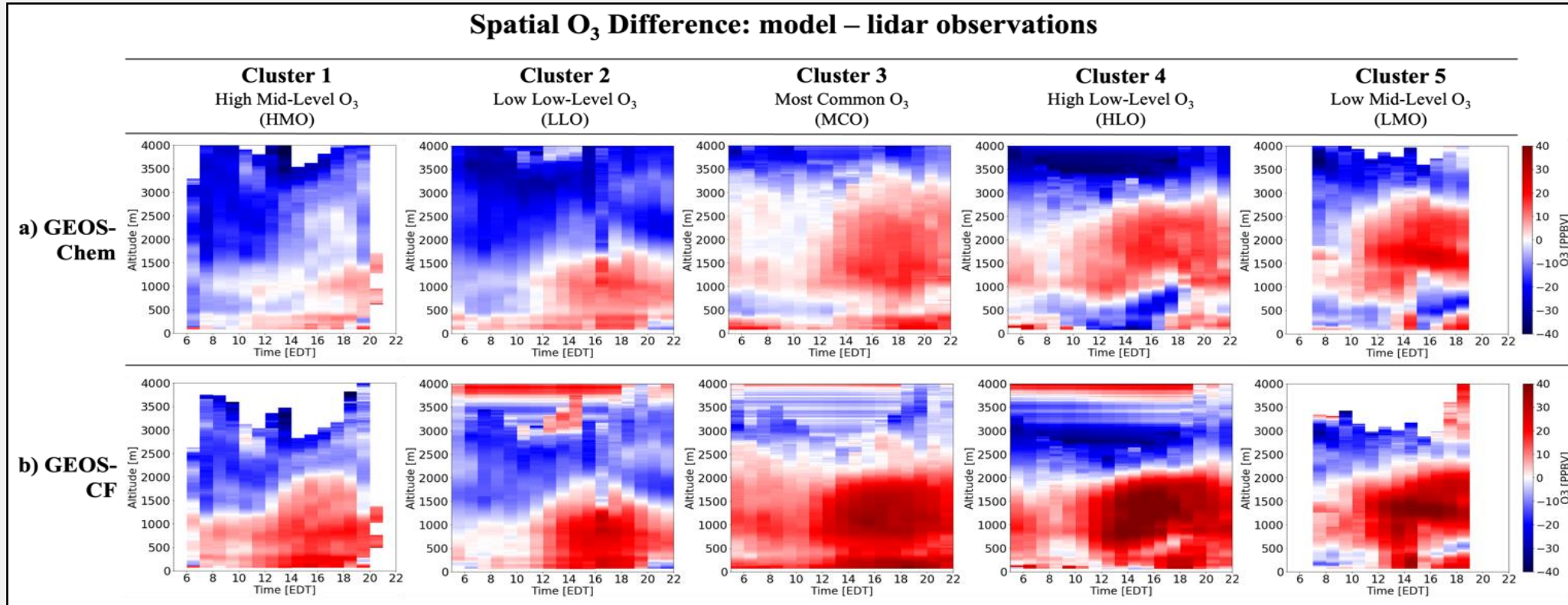


Air Quality Model Results

- Both models simulate low-level O_3 well
- Both models struggle to simulate the magnitude of O_3 in mid-level
- GEOS-Chem simulates low O_3 concentrations best in the low-level altitude (e.g., C2)
- Both models struggled to capture moderately high O_3 in low-level altitudes (e.g., C3)
- Both models underestimate mid-level O_3 with worst performance in C1
- Lower O_3 concentrations are better simulated by both models in mid-level altitudes



Cluster Bias



Low-level bias:

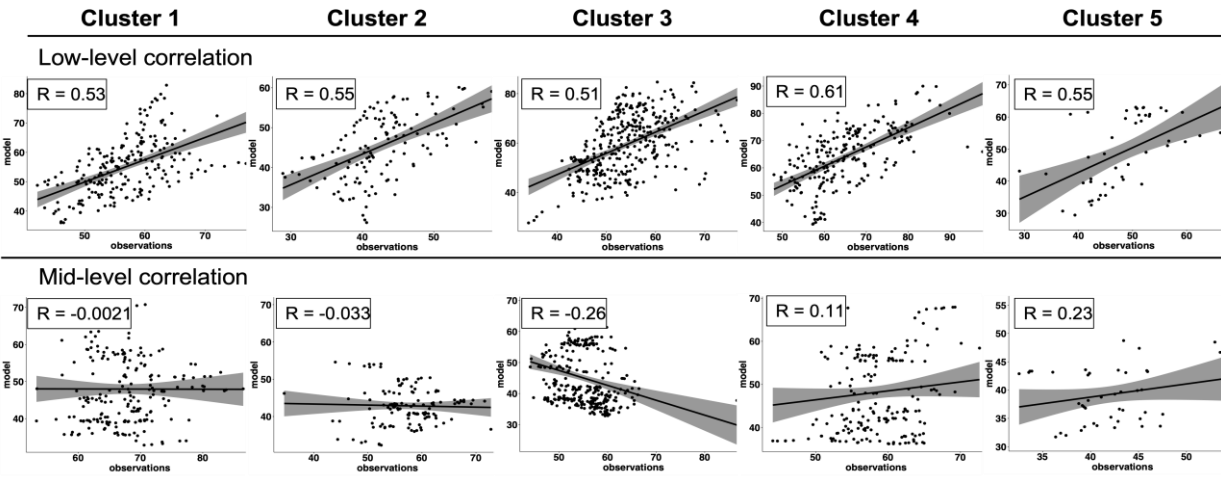
- GEOS-Chem low unsystematic bias range (model – lidar observations)
- GEOS-CF systematic high **+ bias** but fair relationship

Mid-level bias

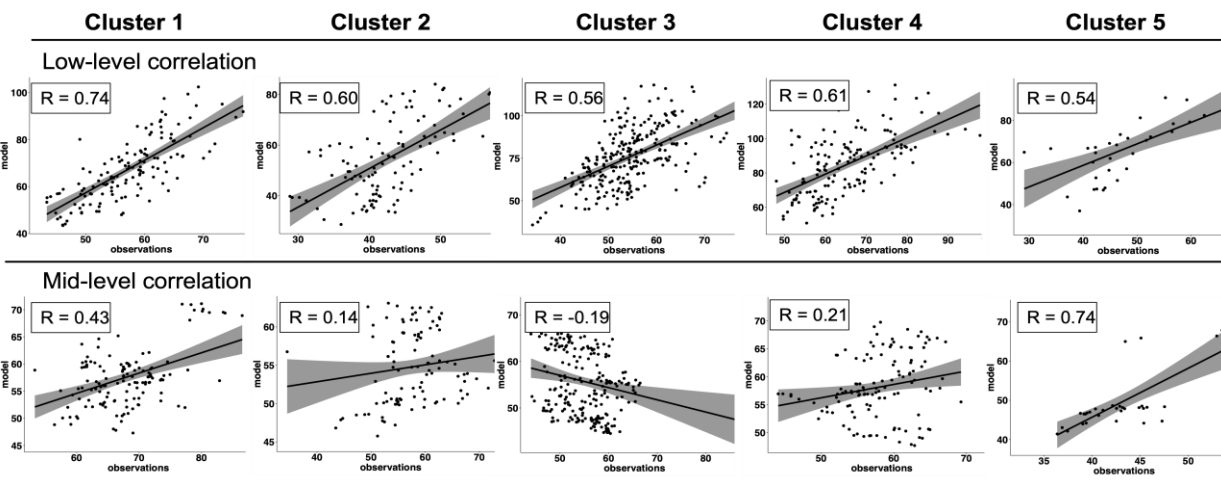
- GEOS-Chem systematic high negative **- bias**
- GEOS-CF low unsystematic bias

Cluster Bias & Correlation

a) GEOS – Chem model



b) GEOS – CF model



Bias varies by cluster for both models.

Low-level bias:

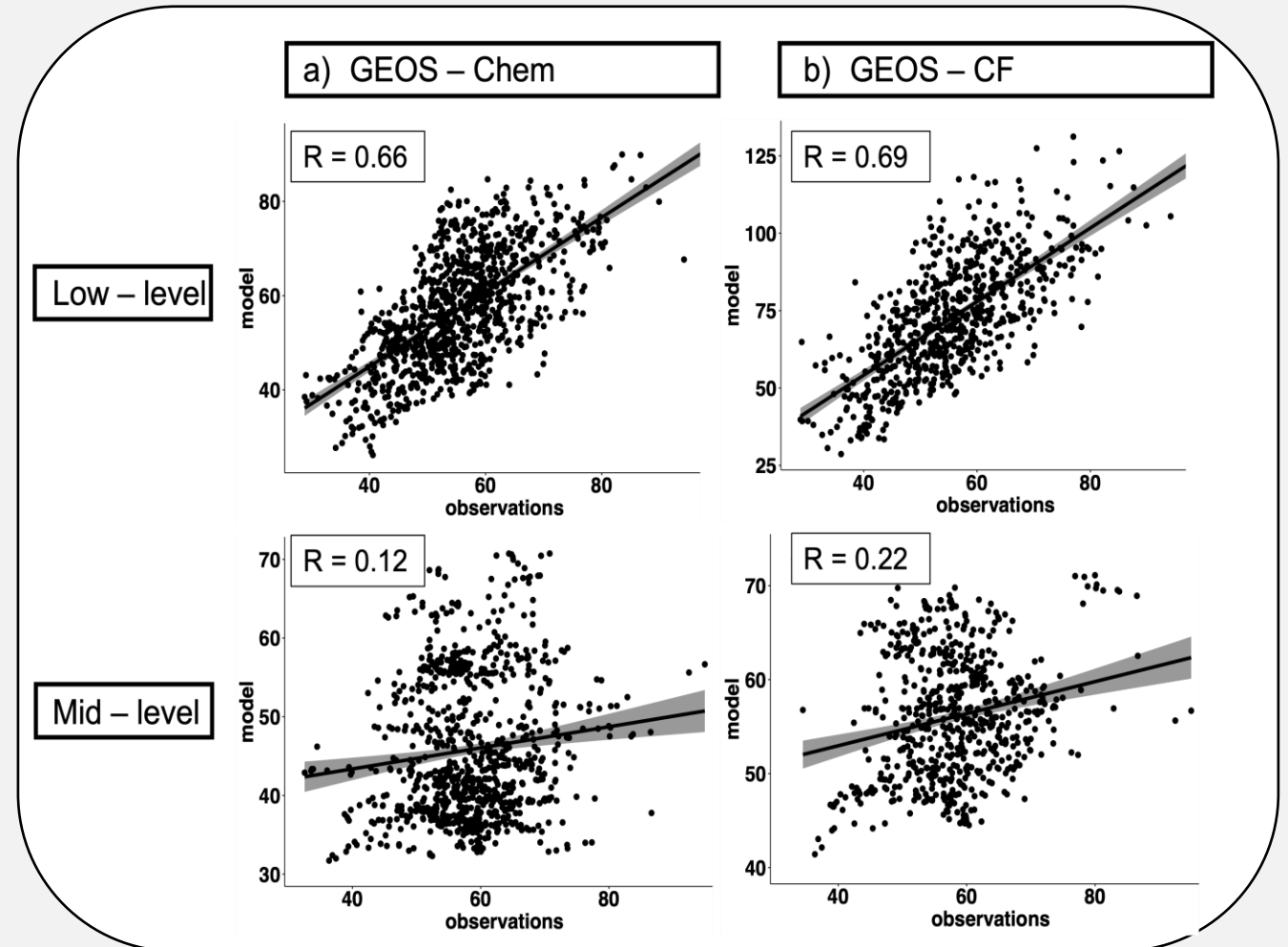
- GEOS-Chem fair relationship with the lidar observations
- Both models able to simulate low-level O_3 pattern well, but GEOS-CF was not able to simulate magnitude consistently overestimating O_3 in low-level altitudes

Mid-level bias:

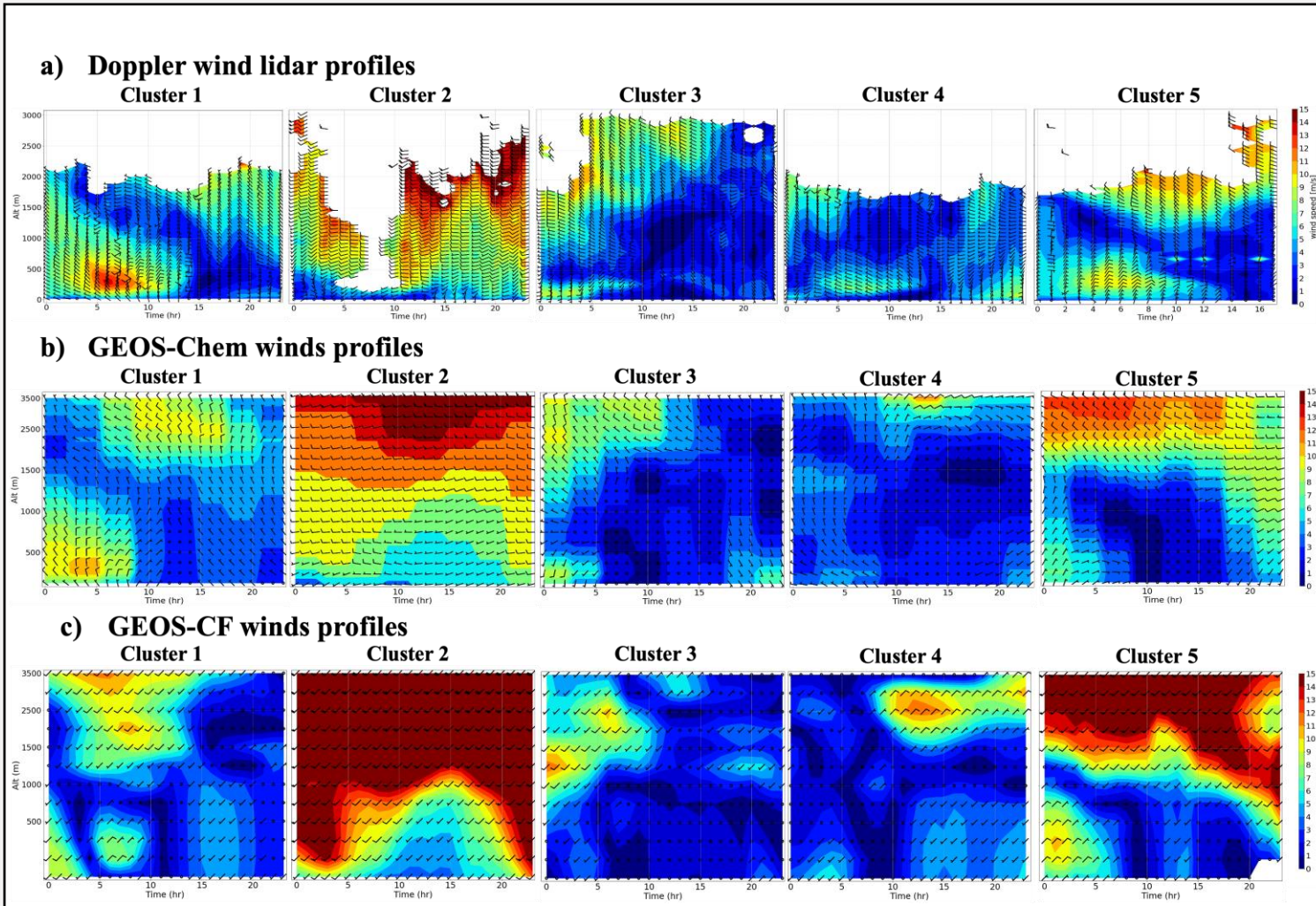
- GEOS-Chem and GEOS-CF both have a weak relationship with the lidar observations
- Neither simulated mid-level O_3 pattern well, but GEOS-CF was able to simulate magnitude slightly better

Overall Model Correlation

- Overall correlation results indicate GEOS-CF (better grid resolution & an online model) had a slightly better relationship with lidar observations than GEOS-Chem
- There are still limitations to both models especially when simulating mid-level O_3
- Known model errors & coarse horizontal and vertical grid resolution contribute to the difficulty in simulating fine-scale coastal O_3 variability

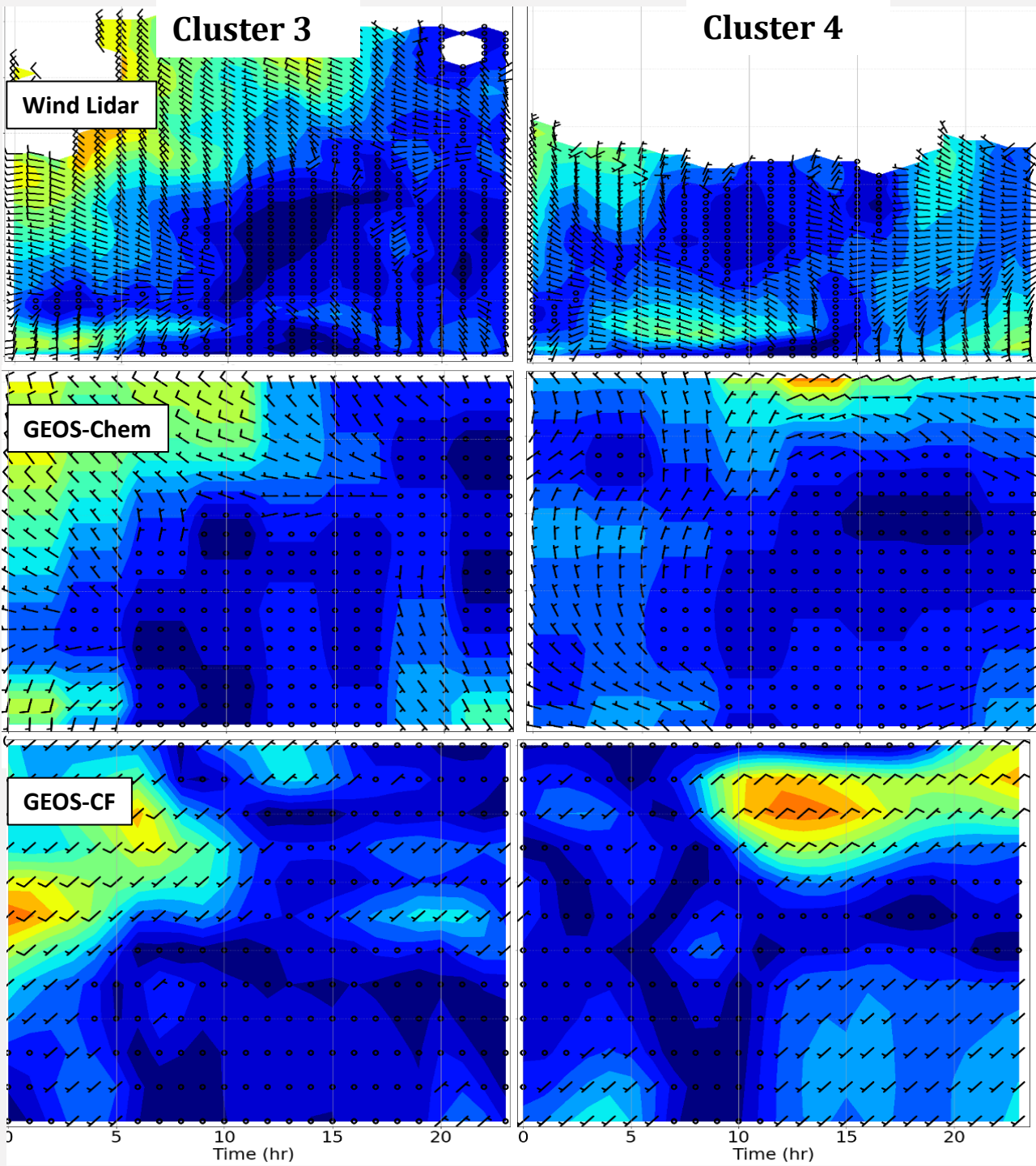


Impact of meteorological factors on clusters & model performance



- Wind lidar data mostly limited (< 2000 m)
- Evaluated Doppler wind lidar vs. simulated wind profiles
- General under prediction in windspeeds
 - Poorest model performance:
 - Cluster 3 & 4
 - Both models had the highest bias & lowest correlation simulating low-level O_3 in Cluster 3
 - The models struggle to capture the finer processes captured by lidar

Fig. Vertical profiles of wind speed and direction from a) Doppler wind lidar, b) GEOS-Chem, and c) GEOS-CF model results from OWLETS-2 at HMI. Each figure depicts a date assigned to a specific cluster (1 - 5).



Sea Breeze cases

- Midday wind deceleration & directional shift (offshore → onshore) at 11:00 LT accompanied by calm winds (0 m/s)
 - Indicating possible common sea/bay breeze event
 - Sea breeze events give cause to enhanced surface O_3
 - Timing of event poorly simulated
 - Models predict little/no wind much earlier in profile (begin at 06:00 LT) & no well-defined shift
 - Coarser model resolution = not able to capture phenomena in these cases
 - Could have facilitated in high O_3 biases for these clusters
-
- Although GEOS-CF has a finer horizontal resolution than GEOS-Chem, results do not reveal advantages simulating wind speed/direction
 - Affirms GEOS-CF spatial resolution (~25 km) still not fine enough for processes such as the sea/bay breeze

Conclusion

- Clustering approach allowed us to characterize a range of variable vertical & temporal coastal O₃ behavior for the duration of these campaigns
- Can be a good indicator of how O₃ behaves in general in coastal regions during summer months
- Clustering analysis provided an abridged method to evaluate performance of two CTMs, GEOS-Chem & GEOS-CF
- Curated clusters reveal current limitations & cases which CTMs fare simulate coastal O₃ well
- Model simulations struggle to reproduce the O₃ vertical profile magnitude, specifically in the mid-level
- Fine processes (sea/bay breeze) were still difficult to simulate even with grid resolutions ...

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Extra:

Clustering application

- Features evaluated for cluster tendency (to confirm dataset contained meaningful clusters)
- Hopkins statistic which measures whether there is uniform distribution (spatial randomness) within dataset (Lawson & Jurs, 1990)
- Results: value higher than 0.75 (actual = 0.77) which by this standard indicates a clustering tendency at the 90% confidence level
- Evaluating different feature options did not lead to better statistical results than with the final chosen features
- *Nbclust* (Charrad et al., 2014) used: applies 30 indices for determining optimal number of clusters
- Tested quality of clustering results using silhouette method (Kaufman & Rousseeuw, 1990)
- Results: 6 clusters – later 5
- K-Means clustering algorithm based on Euclidean distance to each centroid
 - input data normalized (to a mean of zero & standard deviation of one)
 - to ensure each feature is given same importance in clustering (Aksoy & Haralick, 2001; Larose, 2005)

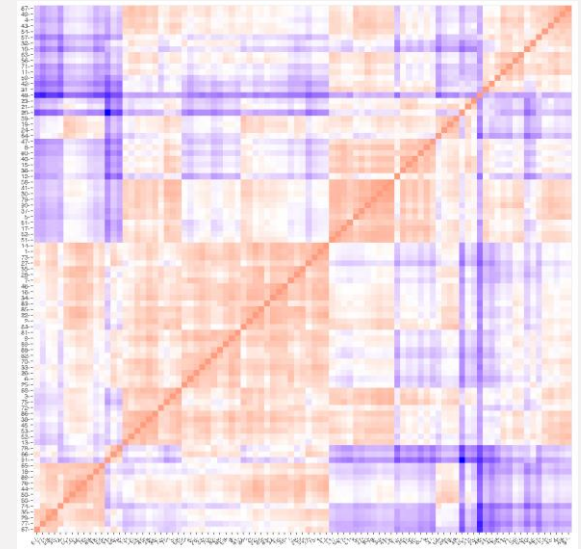


Figure S1. Visual assessment of cluster tendency (VAT) approach. Dataset high similarity (red) and low similarity (blue).

Missing data

- Input features were tailored based on structure of lidar measurements (limitations), remaining data still had missing data points
- Most cases of missing data points:
 - earlier morning measurements (06:00 – 12:00 EDT)
 - later evening measurements (16:00 – 21:00 EDT)
- 51/91 O₃ profile curtains had at least one missing data point (feature)
- Complete case analysis (CCA) (e.g. only 40 O₃ curtains)
- Single imputation (SI) technique (*knnImputation*) to fill in missing data
- Allows use of full 91 profile curtains of O₃ data ~ imputed
- Silhouette method used to test quality of newly imputed dataset
- Proved to be no worse, nor better, than CCA (*real data*) results

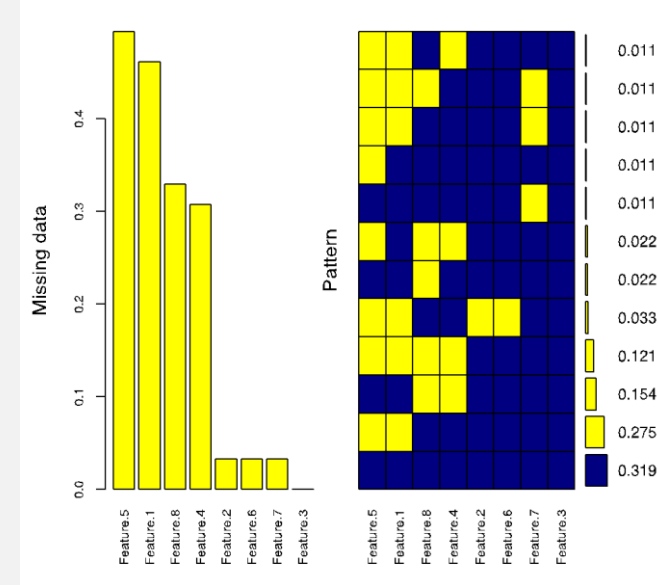


Figure S2. Percentage and pattern of missing data points by each feature used for clustering.